

Towards Empirical Process Theory for Vector-Valued Functions: Metric Entropy of Smooth Function Classes

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Summary

Motivation

Contributions

Vector-valued Learning Problems

- There is a growing literature on learning vector-valued functions:
 - multi-task or multi-output learning;
 - functional response models;
 - kernel conditional mean embeddings;
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- [Caponnetto and de Vito, 2007], [Ciliberto et al., 2020], [Cabannes et al., 2021], [Singh et al., 2019] – Learning rates using integral operator techniques for kernel methods.

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- [Yousefi et al., 2018], [Li et al., 2019] – Vector-valued extension of Rademacher complexities.

Empirical Process Theory for Vector-Valued Functions

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- For example, we're interested in questions such as whether

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- For a class \mathcal{G} of functions $g : \mathcal{X} \rightarrow \mathcal{Y}$, where \mathcal{Y} is a Hilbert space, we are interested in questions such as whether

$$\sup_{g \in \mathcal{G}} \left\| \frac{1}{n} \sum_{i=1}^n g(X_i) - \mathbb{E}[g(X)] \right\|_{\mathcal{Y}} \xrightarrow{P} 0.$$

Metric Entropy

- Suppose (\mathcal{Z}, ρ) is a metric space. For any $\delta > 0$, the δ -covering number of (\mathcal{Z}, ρ) , denoted by $N(\delta, \mathcal{Z}, \rho)$, is the minimum number of balls of radius δ with centres in \mathcal{Z} required to cover \mathcal{Z} . We define the δ -entropy as $H(\delta, \mathcal{Z}, \rho) = \log N(\delta, \mathcal{Z}, \rho)$.

Metric Entropy – Complexity of Function Classes

- For real-valued functions, the following classes of functions have been identified to have good bounds on their metric entropies:
 - Finite-dimensional classes;
 - Classes of smooth functions;
 - Classes of functions of bounded variation;
 - Classes of concave functions;
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- Other measures of complexity also exist, such as the VC dimension and entropy with bracketing.
- For vector-valued function classes, investigations on their metric entropies have not received much attention.

Entropy of Vector-Valued Function Classes

Challenges

- If \mathcal{Y} is infinite-dimensional, seemingly trivial function classes such as the class of constant functions onto the unit ball,

$$\mathcal{G} = \{g(x) = y \text{ for all } x \in \mathcal{X} : y \in \mathcal{Y}, \|y\|_{\mathcal{Y}} \leq 1\}$$

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- To have any chance, it is clear that the output range has to be restricted in more than the norm sense.

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- Let X be a random variable taking values in \mathcal{X} , and X_1, X_2, \dots i.i.d. copies of it.

Fractal Dimensions

- Let E be a subset of (\mathcal{Z}, ρ) . The *upper box-counting dimension* of E is

$$\tau_{\text{box}}(E) := \limsup_{\delta \rightarrow 0} \frac{H(\delta, E, \rho)}{-\log \delta}.$$

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- A subset E of (\mathcal{Z}, ρ) is said to be (M, τ) -*homogeneous* (or simply *homogeneous*) if the intersection of E with any closed ball of radius R can be covered by at most $M \left(\frac{R}{r}\right)^\tau$ closed balls of smaller radius r .

Main Results

- Let $m, d \in \mathbb{N}$, $B \subset \mathcal{Y}$ and \mathcal{X} the unit cube in \mathbb{R}^d .
- Let \mathcal{G}_B^m be the set of m -times differentiable functions $g : \mathcal{X} \rightarrow \mathcal{Y}$ such that:
 - partial derivatives $D^p g : \mathcal{X} \rightarrow \mathcal{Y}$ of orders $[p] \leq m$ exist everywhere on the interior of \mathcal{X} , and
 - $D^p g(x) \in B$ for all $x \in \mathcal{X}$ and $[p] \leq m$.

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Theorem 4

Let $B \subset \mathcal{Y}$ be totally bounded and (M, τ_{asd}) -homogeneous. Then for sufficiently small $\delta > 0$, there exists some constant K depending on K_B , m , d , M and τ_{asd} such that

$$H(\delta, \mathcal{G}_B^m, \|\cdot\|_\infty) \leq K\delta^{-\frac{d}{m}}.$$

Main Results

Theorem 5

Let B be a subset of \mathcal{Y} with finite upper box-counting dimension τ_{box} . Then for sufficiently small $\delta > 0$, there exists some constant K depending on K_B , m , d and τ_{box} such that

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Theorem 6

Let B be a subset of \mathcal{Y} with $N(\epsilon, B, \|\cdot\|_{\mathcal{Y}}) \leq \exp\{M\epsilon^{-\tau_{\text{exp}}}\}$ for some $M, \tau_{\text{exp}} > 0$. Then for sufficiently small $\delta > 0$, there is some constant K depending on K_B , m , d , M and τ_{exp} such that

$$H(\delta, \mathcal{G}_B^m, \|\cdot\|_\infty) \leq K \delta^{-\left(\frac{d}{m} + \tau_{\text{exp}}\right)}.$$

Applications

- Uniform law of large numbers of \mathcal{G}_B^m for B satisfying any of the previous theorems.

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- Regression with smooth functions, where the output space itself consists of smooth (real-valued) functions, or any other real-valued function classes with appropriately bounded entropies.

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- Uniform law of large numbers of \mathcal{G}_B^m for B satisfying any of the previous theorems.
- Regression with smooth functions, where the output space itself consists of smooth (real-valued) functions, or any other real-valued function classes with appropriately bounded entropies.
- Kernel conditional mean embeddings, where the outputs consist of functions taking values in an RKHS.

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- Our work attempts to make some first steps in developing empirical process theory for vector-valued functions.
- Future directions:
 - entropy of function classes other than those of smooth functions;
 - infinite-dimensional input spaces;
 - uniform central limit theorems;
 - lower bounds... and many more.